

INTEGRATION OF

AGVs AND MOBILE ROBOTS IN THE MANUFACTURING INDUSTRY

TAKE THE FIRST STEPS DURING OUR WORKSHOP

OPTIMISE YOUR PRODUCTION PROCESS WITH AGVs AND MOBILE ROBOTS.

Having an effective production process is critical to staying relevant to your customers and being agile in this ever-changing world. However, the rapid advancements in the market bring forth their own unique set of difficulties, such as the shortage of (logistics) personnel, soaring labour costs, rivalry from countries with low wages, and a demand to stay relevant to your customers.

Optimisation and automation of the production processes, coupled with the introduction of Automated Guided Vehicles (AGV) and Mobile Robots, can help maximise the output of your facility without increasing the workload of employees. But, how can these changes be implemented within the existing framework? What are the challenges? And, how can these be addressed?

At the 'Integration of AGVs and Mobile Robots in the Manufacturing Industry' workshop, Twin Tech and AMRobotics will share their knowledge when it comes to the application of software and hardware. Additionally, an entrepreneur with hands-on

experience with AGVs and Mobile Robots in their own production and logistics processes will share their experience and offer insights. With the guidance of experts, you will have the opportunity to engage in structured discussions and learn the steps necessary to capitalise on the potential offered by AGVs and Mobile Robots. Upon completion, you will be able to understand the possibilities, anticipate potential pitfalls, and devise concrete strategies to begin your AGV/ Robotics integration journey. Please note that the workshop will be conducted in Dutch.

SIGN UP NOW FOR FREE:



Thursday

13 April 2023

9:00 AM - 1:00 PM

Language: Dutch

For whom:

Engineers, Production and Operations Managers, and (Technical) Directors

Location

Fraunhofer Innovation Platform for Advanced Manufacturing at the University of Twente Hengelosestraat 701 7521 PA Enschede